IRB 6400

Industrial Robot

MAIN APPLICATIONS

Spot welding Press tending Material handling Machine tending Palletizing Assembly



High performance industrial robot

The 6-axis IRB 6400 manipulator and S4Cplus robot controller provide short and precise cycle times, rapid change-overs and consistently high process precision. IRB 6400 accounts for one third of the 90,000 ABB robot installations.

The family of 6400 robots consists of different arm variants and payload categories which are controlled by the advanced dynamic model based control function, QuickMoveTM, always ensuring the highest acceleration, path accuracy and speed over the entire working envelope.

Adaptability

IRB 6400 is designed to be compact with a small interference radius to ensure flexible installations in

areas with high density of production equipment. The process media, which is integrated through the robot base is easily exchanged and changing from a 2.5 to 3 meter overarm takes less than 30 minutes. The robot can be calibrated one axis at a time to ensure a quick return to full production.

Reliability and safety

IRB 6400 features robust all-steel construction with high material strength. The arms are mechanically balanced and equipped with double bearings. Advanced motion control and collision detection option greatly reduce the risk of tool and workpiece damage, making this a highly reliable and safe robot.



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TECHNICAL DATA, IRB 6400 INDUSTRIAL ROBOT

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	ot versions	Reach to	Handling	Remarks
IRB		5 th axis	capacity	
6400)R/3.0-100	3.0 m	100 kg	
6400)R/2.5-120	2.5 m	120 kg	
6400)R/2.5-150	2.5 m	150 kg	
6400	R/2.8-150	2.8 m	150 kg	
6400)R/2.5-200	2.5 m	200 kg	
6400)R/2.8-200	2.8 m	200 kg	
6400)S/2.9-120	2.9 m	120 kg	Shelf
6400)PE	2.25 m	5000 N	Poke welding

All IRB 6400R-versions have Foundry Plus protection. For details, see under Environment.

Supplementary load

3.0-100, 2.8-200, 2.5-120,

2.5-150, 2.5-200 and 2.8-150 50+320 kg Others 35+320 kg

Number of axes

Robot manipulator 6 External devices

10 poles 50 V DC Integrated signal supply

2 poles 250 V AC 2 CAN-Buses

0.1 mm

0.15 mm

Integrated air supply Max. 10 bar

PERFORMANCE

Position repeatability	
2.5-120 and 2.5-150	
Others	

Path repeatability at 1 m/s (based on ISO path) 2.5-120 and 2.5-150 1.0 mm Others 1.5 mm

Max. TCP velocity on ISO-plane >2-3 m/s Max. TCP acceleration on ISO-plane >10 m/s²

Axis working range

7 Kilo Working range				
	Axis	Shelf	PE	Others
Positioning	1 Rotation	360°	360°	360°
	2 Arm	130°	140°	155°
	3 Arm	108°	133°	138°
Reorientation	4 Wrist	600°	400°	600°
	5 Bend	240°	240°	240°
	6 Turn	600°	600°	600°

Axis maximum speed, °/s						
		2.5-120	2.5-150	2.8-200	PE	Shelf
		3.0-100	2.5-200			
Axis 2.8-150						
Positioning	1 Rotation	110	100	90	70	100
	2 Arm	100	90	70	70	100
	3 Arm	100	90	70	70	100
Reorientation	4 Wrist	210	120	110	210	210
	5 Bend	150	120	110	150	150

210

Max. force, PE 5000 N

ELECTRICAL CONNECTIONS

Supply voltage	200–600 V, 50/60 Hz
Rated power, supply transformer	7.2 - 7.8 kVA

110

210 210

PHYSICAL

Dimensions manipulator base

IRB 6400R 1070 x 1050 mm 1044 x 922 mm 1044 x 922 mm IRR 6400S IRB 6400PE

Weight manipulator

1600 kg 2060 - 2390 kg 6400PE Others

ENVIRONMENT

Ambient temperature

5 - 50°C Manipulator Relative humidity Max. 95%

Degree of protection

Foundry plus (all IRB 6400R versions) IP 67 and washable Foundry (IRB 6400S)

Wrist IP 67, the rest IP 55 Noise level Max. 70 dB (A)

Safety Double circuits with supervision, emergency stops and safety functions, 3-position enable device Emmission EMC/EMI-shielded

Data and dimensions may be changed without notice

WORKING RANGE AND LOAD DIAGRAM

IRB 6400PF 600 400 200 878 200







